Distributed Systems

ID2201

coordination and agreement I

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Coordination

- Coordination in a distributed system:
  - no fixed coordinator
  - no shared memory
  - failure of nodes and networks
- Coordination is often the problem of:
  - deciding who is to decide
  - knowing who is alive.

Fundamental models

- Interaction model:
  - asynchronous or synchronous
  - Can we assume a node has crashed if it does not reply?
- Failure model:
  - Will nodes crash?
  - Will crash nodes return to life?
  - Is crashing the only failure?

Distributed algorithms

- We will look at some distributed algorithms and assume:
  - that nodes are correct
  - that messages are delivered

Three sides of the same coin

- Mutual exclusion
  - who is to enter a critical section
- Leader election
  - who is to be the new leader
- Atomic multicast
  - which messages
  - which order

Distributed mutual exclusion

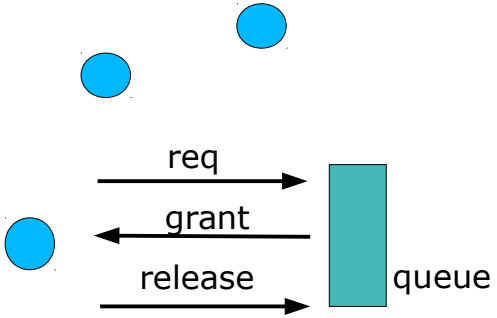
- **Safety:**
  - at most one process may be in critical section at a time
- **Liveness:**
  - *starvation free*
  - deadlock free
- **Ordering:**
  - enter in *request happened-before* order

Evaluation

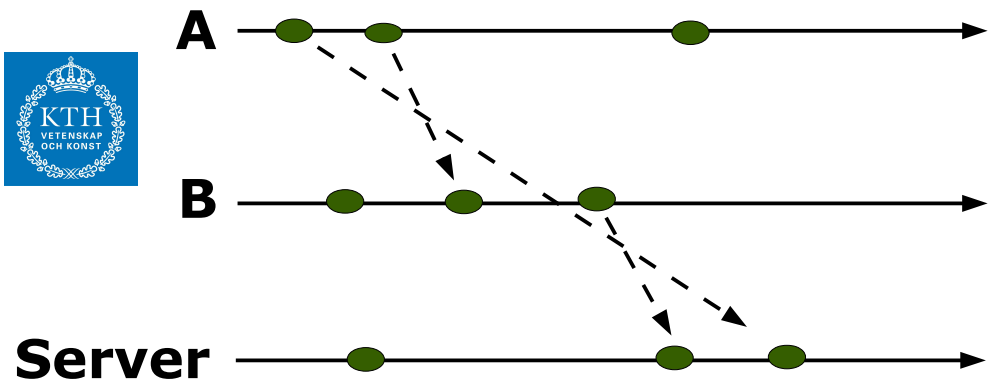
- Number of messages needed.
- Client delay:
  - time to enter critical section
- Synchronization delay:
  - time between exit and enter

Central service algorithm

- Requirements?
  - safety
  - liveness
  - ordering



Ordering - what is a request

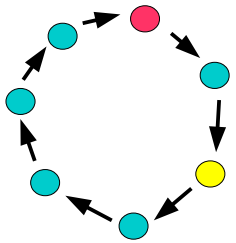


Performance

- messages
  - enter: request, grant
  - exit: release
- client delay
  - enter: message round trip plus waiting in queue
  - exit: constant (asynchronous message)
- synchronization delay
  - round trip: release - grant

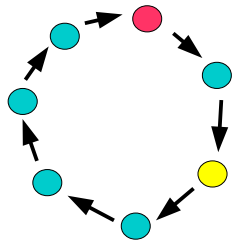
Ring-based algorithm

- Requirements
  - safety
  - liveness
  - ordering



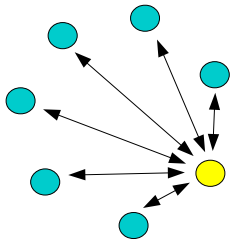
Ring-based algorithm

- Performance
  - messages
  - client delay
  - synchronization delay



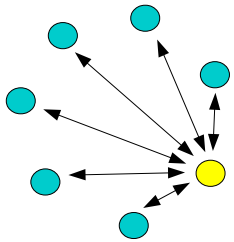
Distributed algorithm

- Send request to all peers.
- When all peers have acknowledged the request, enter the critical section.
- What could go wrong?



Distributed algorithm

- Break deadlock
  - introduce priority
- Fairness
  - Ricart and Agrawala



Ricart and Agrawala

- Enter:
  - enter state waiting and broadcast a request {T,i} containing a *Lamport time stamp T* and process id I to all peers
  - wait for replies from all peers
  - enter state held
- Receiving a request {R,j}:
  - if *held or (waiting* and {T,i} < {R,j}) then queue request, else reply ok
- Exit:
  - reply to all queued requests

Ricart and Agrawala

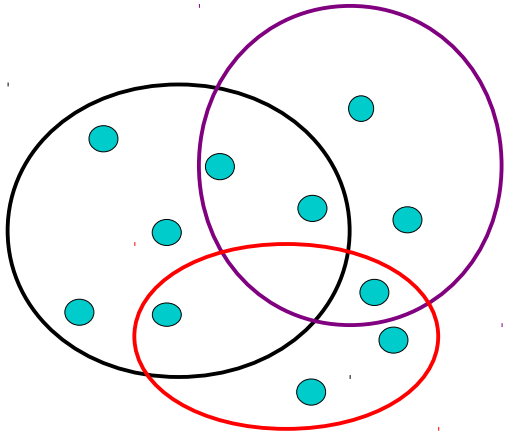
- Requirements
  - safety, liveness, ordering
- Efficiency
  - messages
  - client delay
  - synchronization delay

Maekawa's voting

- Why have permission from all peers?
  - it's sufficient to have votes from a subset S,
  - if no one can enter with the votes from the complement of S.
- The subset S is called a *quorum.*

Maekawa's voting

- Requirements
  - safety
  - liveness
  - ordering



Maekawa's voting

- Efficiency
  - messages
  - client delay
  - synchronization delay

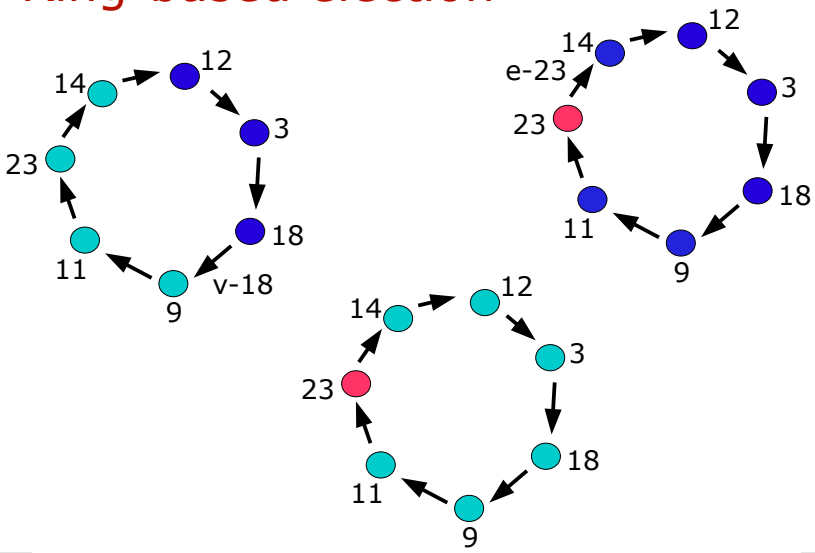
Election

- Many algorithms require a leader but if no node is assigned to be the leader one has to be elected.
- Assumptions:
  - any node can *call an election,* but it can only call one at a time
  - a node is either *participant* or *non-participant*
  - nodes have identifiers that are ordered

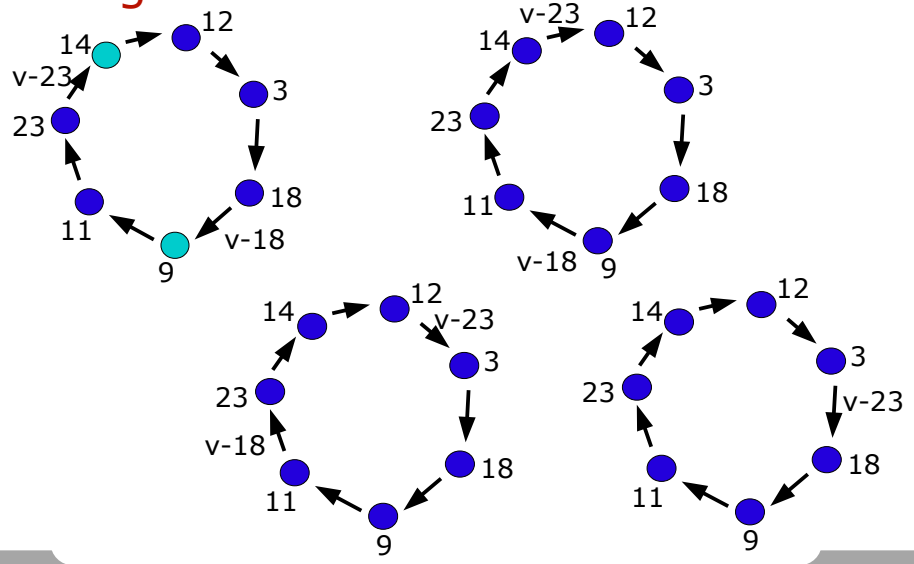
Election

- Requirements
  - safety: a *participant* is either non-decided or decided with P, a unique non crashed node
  - liveness: all nodes eventually *participate* and decide on a elected node
- Efficiency
  - number of messages
  - turnaround time: delay from *call* to *close*

Ring-based election



Ring-based election



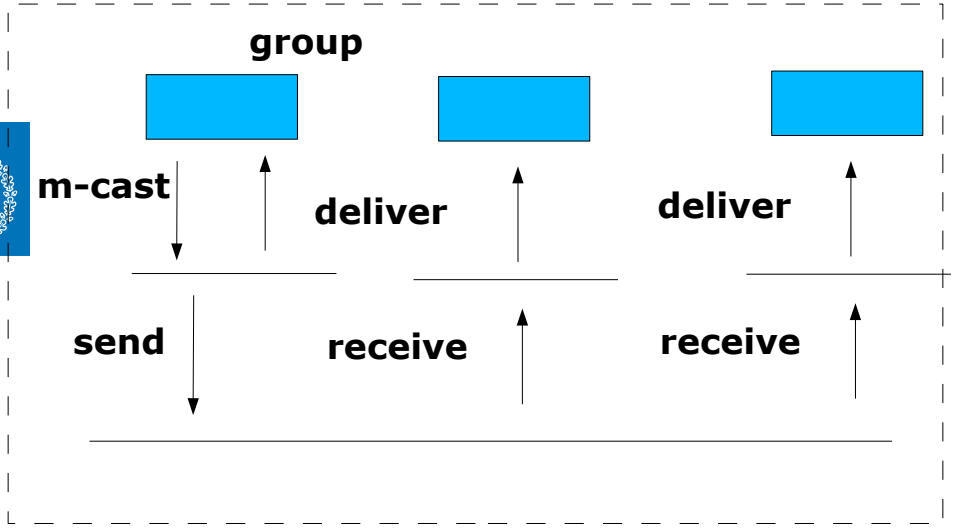
Ring-based election

- Requirements
  - safety
  - liveness
- Efficiency
  - messages: best case, worst case?
  - turnaround:

Multicast communication

- Multicast:
  - Sending a message to a specified group of n nodes.
- Atomic multicast:
  - All nodes see the same messages in the same order.

Model



Requirements

- Integrity
  - a process *delivers* a message at most once and only deliver messages that have been sent
- Validity
  - if a process multicast m then it will also eventually deliver m
- Agreement
  - if a process *delivers m* then all processes in the group eventually *delivers m*

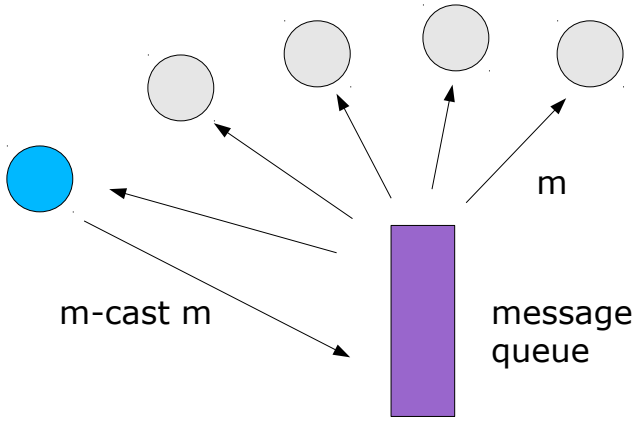
Basic multicast

- To b-multicast a message m:
  - send m to each process p
- If m is received:
  - b-deliver m
- What was the problem?

Ordered multicast

- The problem with the basic multicast is that multicast messages might arrive in different order at different nodes.
- Requirements:
  - FIFO order: delivered in order as sent by the sender
  - Causal order: delivered in *happened before* order
  - Total order: delivered in *same order* by all processes

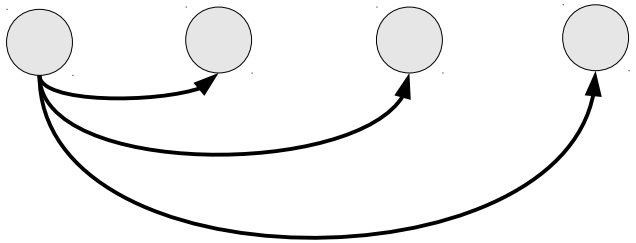
Sequencer



Distributed - ISIS

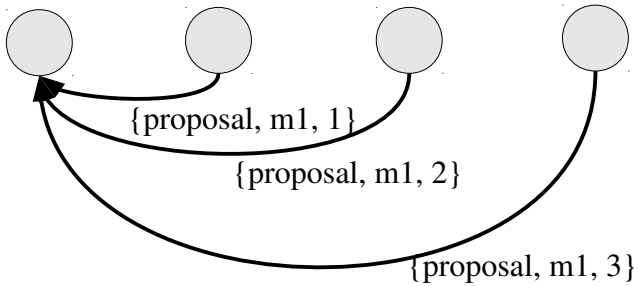
- Multicast a message and request a sequence number.
- When receiving a message, *propose a sequence number (including process id)* and place in an ordered hold-back queue.
- After collecting all proposals, select the highest and multicast agreement.
- When receiving agreement tag message as agreed and reorder hold-back queue.
- If first message in queue is decided then deliver.

Distributed - ISIS

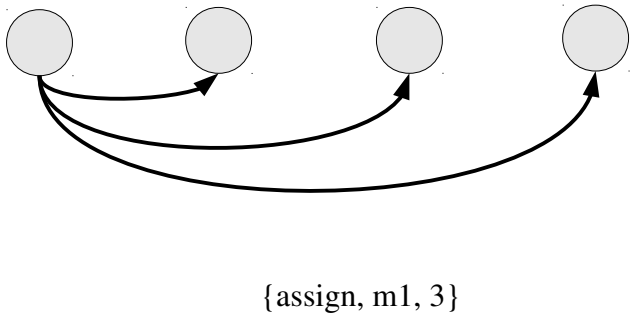


{request, m1, ...}

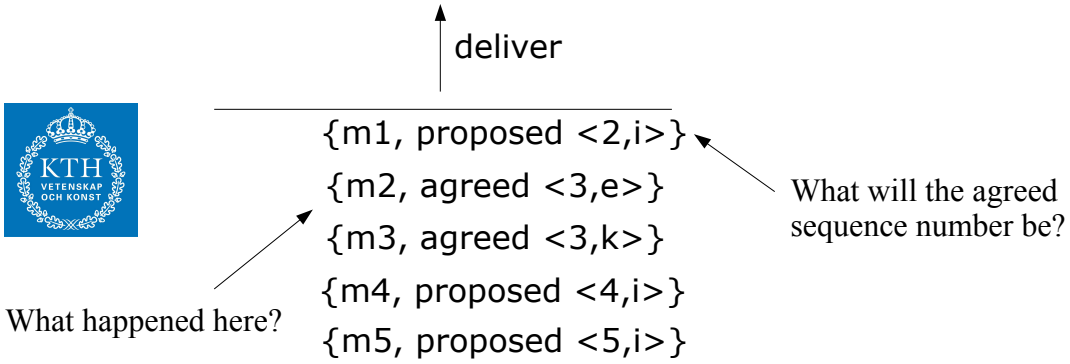
Distributed - ISIS



Distributed - ISIS



the hold-back queue



Causal ordering

- How can we implement casual ordering?
  - multicast vector clock holds number of multicast operations
  - tag each multicast message with multicast clock
  - hold b-delivered messages until clock of message is *less* (modulo sender) than own current message clock
  - update own message clock
- Only multicasted messages are counted.

Summary

- Coordination in distributed systems is problematic.
- Three sides of the same coin:
  - mutual exclusion
  - leader election
  - atomic multicast
- If nodes fail
  - next lecture